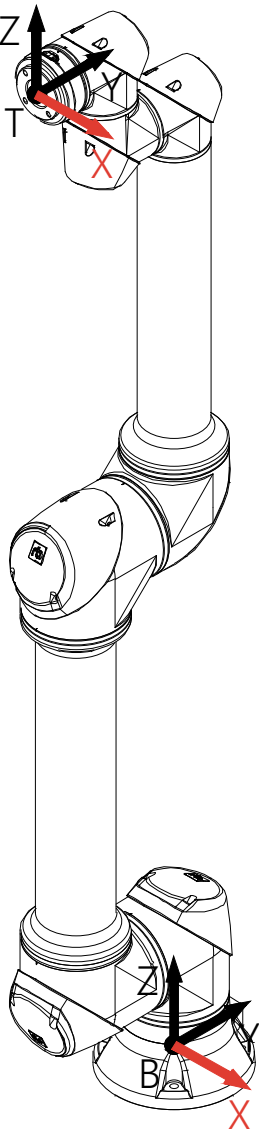
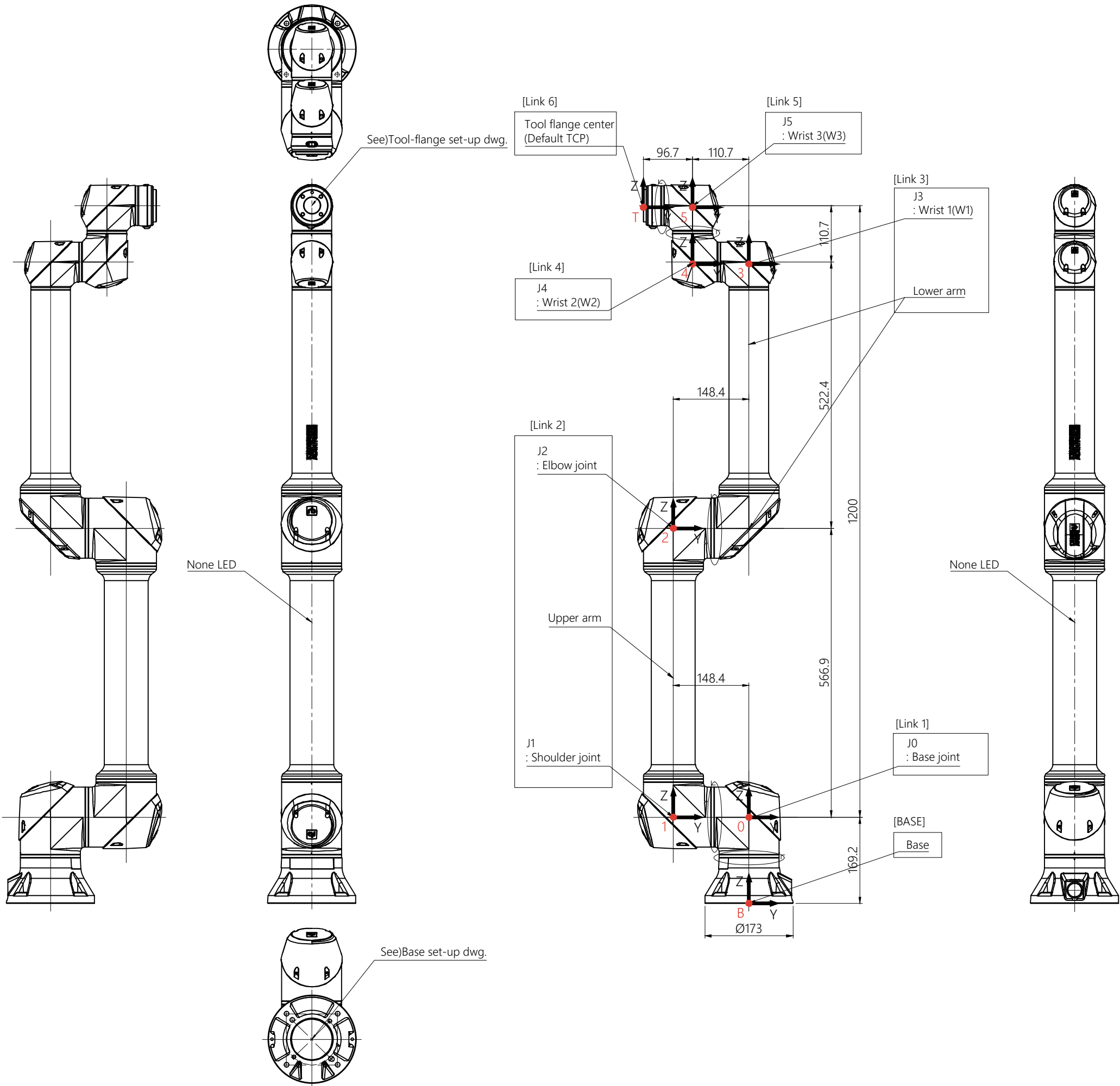




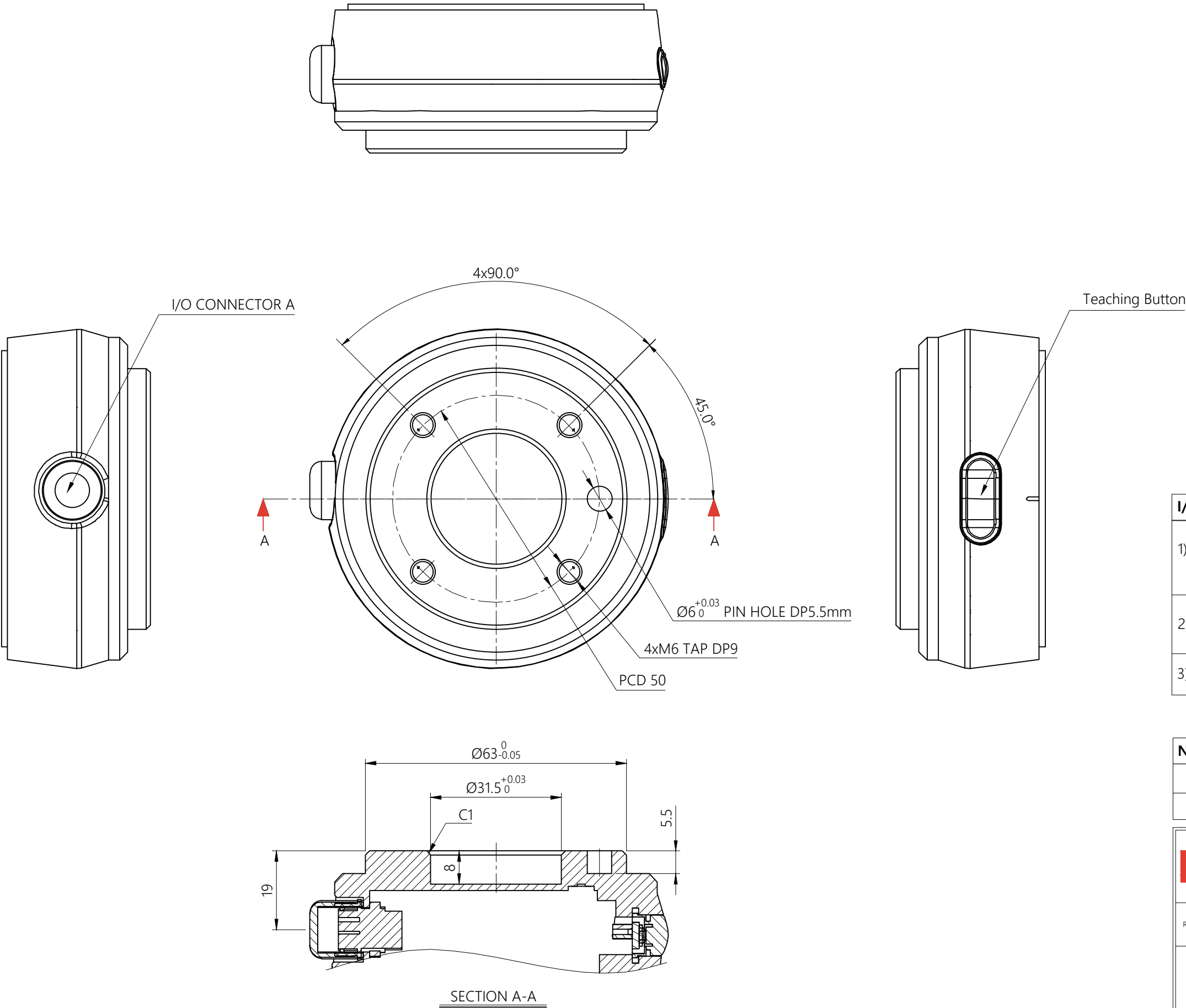
REVISIONS					
ECN	부호	날짜	내용	수정자	승인자
-	-	2022.00.00	-	-	J.W HEO



NOTE	
1)	This drawing is an assembly drawing of RB3-1200EN.



	PART NAME RB3-1200EN A'SSY(E-Version)			
	DRAWING NO. -			Rev -
THIS DRAWING MAY NOT BE REPRODUCED WITHOUT PRIOR WRITTEN APPROVAL.	SCALE 1:1	MATERIAL -	DRN. BY T.K AHN	2024.01.18
	TOLERANCE UNLESS OTHERWISE SPECIFIED: XXX : ±0.2 XX : ±0.1 X : ±0.1 X.X : ±0.05 ANGLE : ±0.5°  단위 : MM	SIZE A1	CHK'D. BY -	-
REFERENCE -			APPR'D BY J.W HEO	2024.01.18
Page 1 of 1				
		COPYRIGHT (C) RAINBOW ROBOTICS CORP. ALL RIGHTS RESERVED.		

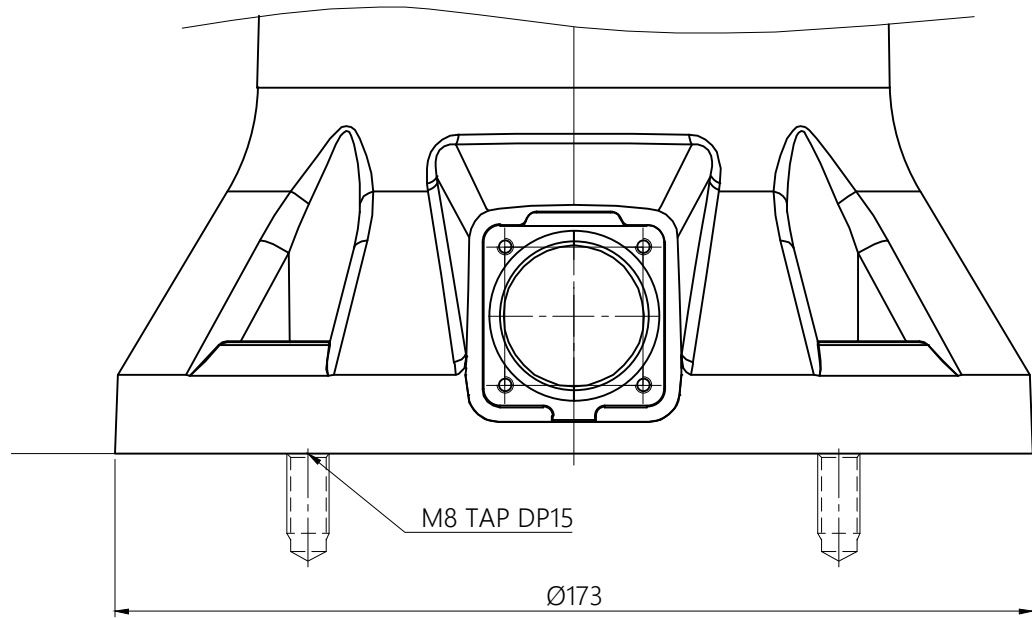
REVISIONS					
ECN	부호	날짜	내용	수정자	승인자
-	-	2022.00.00	-	-	J.W HEO



I/O Connector A	
1) I/O Connector	- M12xP0.5 female circular connector, 12pin - Spec : SW-10W-12(R) - Maker : Sam Woo Electronics
2) Cable	- M12xP0.5 male circular connector, 12pin - Spec : SW-10W-12(P) - Maker : Sam Woo Electronics
3) CAP	- M12 knurling cap - Maker : Rainbow-Robotics

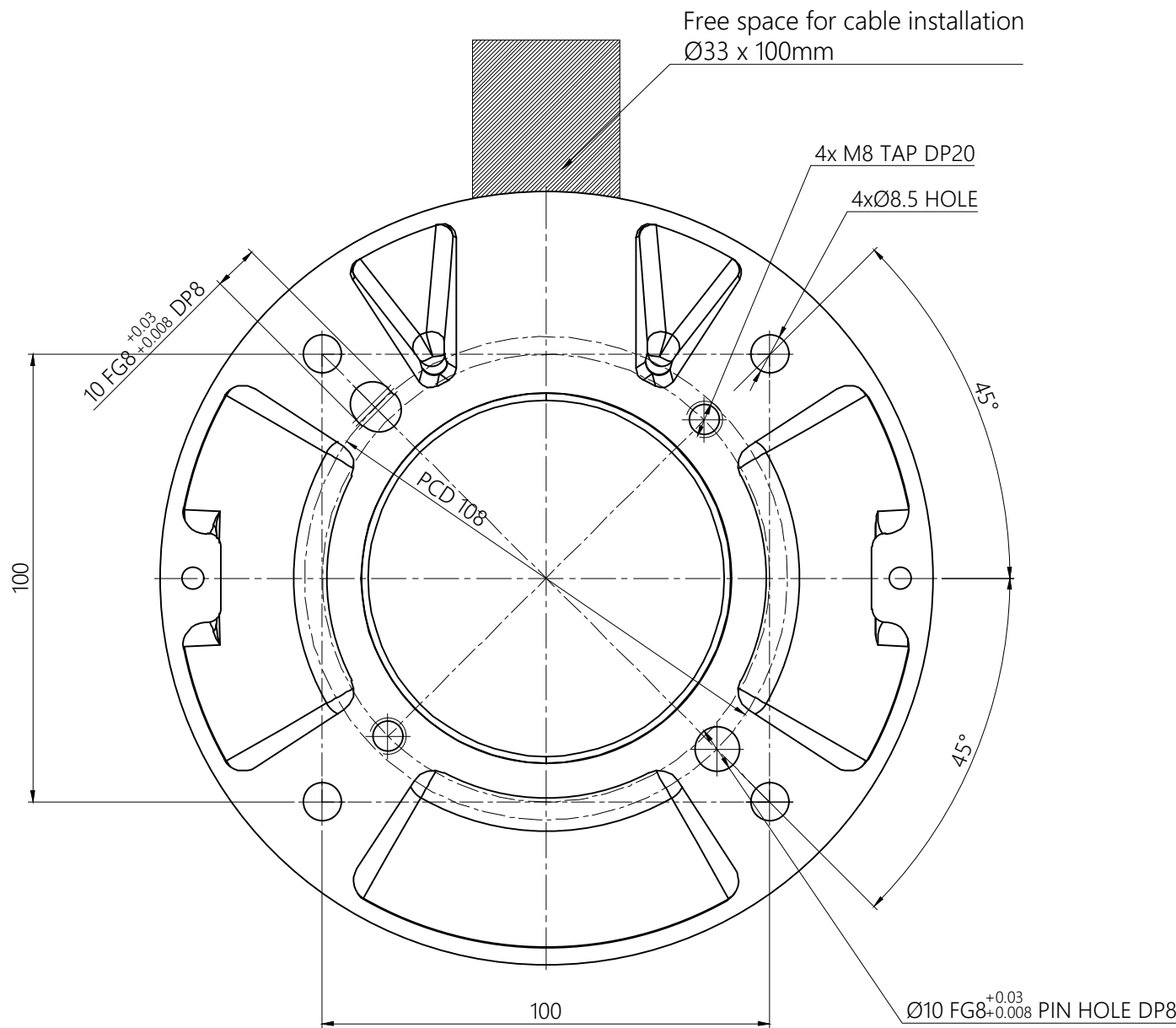
NOTE	
1)	This drawing is a "Tool flange set-up" drawing.
2)	Mechanical interfaces : ISO 9409-1-50-4-M6

	PART NAME Tool flange set up_RB3-1200E/RB5-850E(E-Version)			
	DRAWING NO. -			Rev -
THIS DRAWING MAY NOT BE REPRODUCED WITHOUT PRIOR WRITTEN APPROVAL.	SCALE  1:1	MATERIAL  -	DRN. BY T.K AHN	2024.01.18
	TOLERANCE UNLESS OTHERWISE SPECIFIED:  XXX : ±0.2 XX : ±0.1 X : ±0.1 X.X : ±0.05 ANGLE : ±0.5°	SIZE  A3	CHK'D. BY -	-
REFERENCE  -			APPR'D BY J.W HEO	2024.01.18
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Surface on which the robot is fitted

0.05



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ECN	부호	날짜	내용	수정자	승인자
-	-	2022.00.00	-	-	J.W HEO

NOTE

- 1) This drawing is a "Base set-up" drawing.

	PART NAME Base set-up_RB3-1200E/RB5-850E(E-Version)			
	DRAWING NO. -			Rev -
THIS DRAWING MAY NOT BE REPRODUCED WITHOUT PRIOR WRITTEN APPROVAL.	SCALE 1:1	MATERIAL -	DRN. BY T.K AHN	2024.01.18
			CHK'D. BY -	-
TOLERANCE UNLESS OTHERWISE SPECIFIED: XXX: ±0.2 XX: ±0.1 X: ±0.1 XX: ±0.05 ANGLE: ±0.5°	SIZE A2	REFERENCE -	APPR'D BY J.W HEO	2024.01.18
			Page 1 of 1	
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